

# DATA SHEET

For a complete data sheet, please also download:

- The IC04 LOCMOS HE4000B Logic Family Specifications HEF, HEC
- The IC04 LOCMOS HE4000B Logic Package Outlines/Information HEF, HEC

## **HEF4015B**

## **MSI**

## **Dual 4-bit static shift register**

Product specification  
File under Integrated Circuits, IC04

January 1995

# Dual 4-bit static shift register

# HEF4015B MSI

**DESCRIPTION**

The HEF4015B is a dual edge-triggered 4-bit static shift register (serial-to-parallel converter). Each shift register has a serial data input (D), a clock input (CP), four fully buffered parallel outputs (O<sub>0</sub> to O<sub>3</sub>) and an overriding asynchronous master reset input (MR). Information

present on D is shifted to the first register position, and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of CP. A HIGH on MR clears the register and forces O<sub>0</sub> to O<sub>3</sub> to LOW, independent of CP and D. Schmitt-trigger action in the clock input makes the circuit highly tolerant to slower clock rise and fall times.

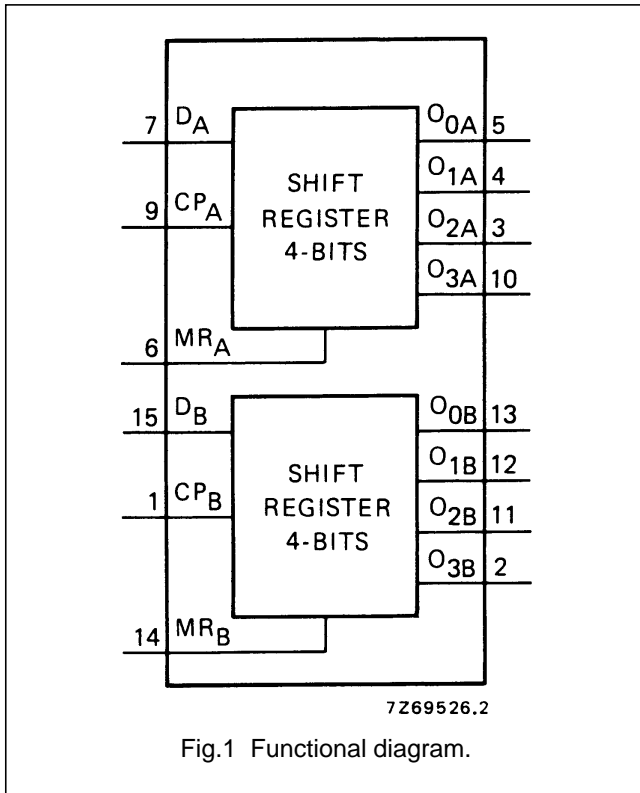


Fig.1 Functional diagram.

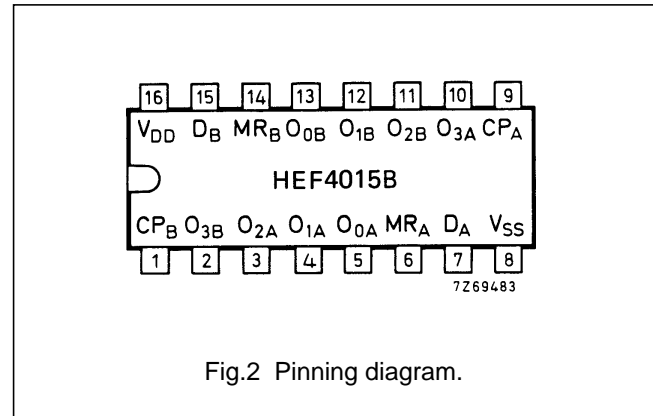


Fig.2 Pinning diagram.

- HEF4015BP(N): 16-lead DIL; plastic (SOT38-1)
- HEF4015BD(F): 16-lead DIL; ceramic (cerdip) (SOT74)
- HEF4015BT(D): 16-lead SO; plastic (SOT109-1)
- ( ): Package Designator North America

**PINNING**

- D<sub>A</sub>, D<sub>B</sub> serial data input
- MR<sub>A</sub>, MR<sub>B</sub> master reset input (active HIGH)
- CP<sub>A</sub>, CP<sub>B</sub> clock input (LOW-to-HIGH edge-triggered)
- O<sub>0A</sub>, O<sub>1A</sub>, O<sub>2A</sub>, O<sub>3A</sub> parallel outputs
- O<sub>0B</sub>, O<sub>1B</sub>, O<sub>2B</sub>, O<sub>3B</sub> parallel outputs

**APPLICATION INFORMATION**

Some examples of applications for the HEF4015B are:

- Serial-to-parallel converter
- Buffer stores
- General purpose register

**FAMILY DATA, I<sub>DD</sub> LIMITS category MSI**

See Family Specifications

Dual 4-bit static shift register

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LOGIC DIAGRAM (one register)

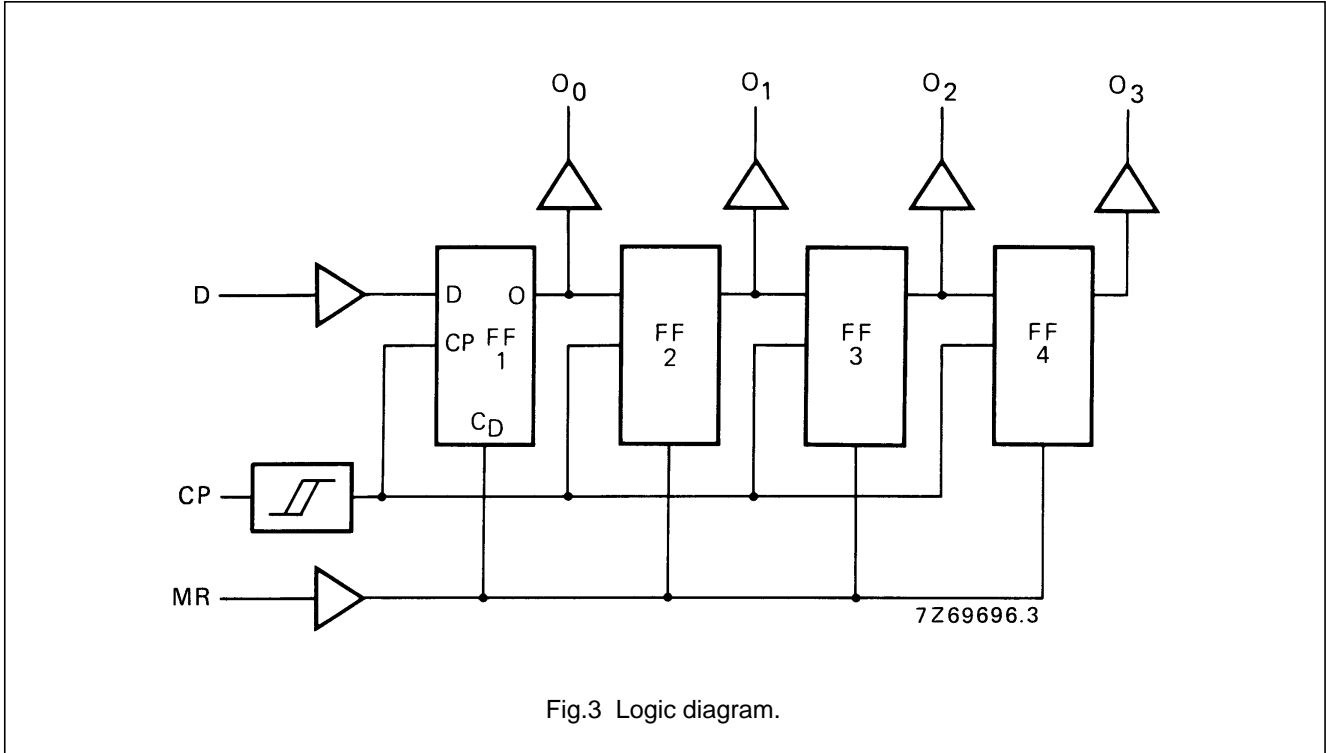


Fig.3 Logic diagram.

FUNCTION TABLE

n	INPUTS			OUTPUTS			
	CP	D	MR	O <sub>0</sub>	O <sub>1</sub>	O <sub>2</sub>	O <sub>3</sub>
1		D <sub>1</sub>	L	D <sub>1</sub>	X	X	X
2		D <sub>2</sub>	L	D <sub>2</sub>	D <sub>1</sub>	X	X
3		D <sub>3</sub>	L	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	X
4		D <sub>4</sub>	L	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>
		X	L	no change			
	X	X	H	L	L	L	L

Note

1. H = HIGH state (the more positive voltage)
2. L = LOW state (the less positive voltage)
3. X = state is immaterial
4. = positive-going transition
5. = negative-going transition
6. D<sub>n</sub> = either HIGH or LOW
7. n = number of clock pulse transitions

## Dual 4-bit static shift register

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MSI**AC CHARACTERISTICS** $V_{SS} = 0\text{ V}$ ;  $T_{amb} = 25\text{ °C}$ ;  $C_L = 50\text{ pF}$ ; input transition times  $\leq 20\text{ ns}$ 

	$V_{DD}$ V	SYMBOL	MIN.	TYP.	MAX.	TYPICAL EXTRAPOLATION FORMULA	
Propagation delays CP $\rightarrow$ O <sub>n</sub> HIGH to LOW	5	$t_{PHL}$		130	260	ns	103 ns + (0,55 ns/pF) $C_L$
	10			55	110	ns	44 ns + (0,23 ns/pF) $C_L$
	15			40	80	ns	32 ns + (0,16 ns/pF) $C_L$
LOW to HIGH	5	$t_{PLH}$		120	240	ns	93 ns + (0,55 ns/pF) $C_L$
	10			55	110	ns	44 ns + (0,23 ns/pF) $C_L$
	15			40	80	ns	32 ns + (0,16 ns/pF) $C_L$
MR $\rightarrow$ O <sub>n</sub> HIGH to LOW	5	$t_{PHL}$		105	210	ns	78 ns + (0,55 ns/pF) $C_L$
	10			45	90	ns	34 ns + (0,23 ns/pF) $C_L$
	15			35	70	ns	27 ns + (0,16 ns/pF) $C_L$
Output transition times HIGH to LOW	5	$t_{THL}$		60	120	ns	10 ns + (1,0 ns/pF) $C_L$
	10			30	60	ns	9 ns + (0,42 ns/pF) $C_L$
	15			20	40	ns	6 ns + (0,28 ns/pF) $C_L$
LOW to HIGH	5	$t_{TLH}$		60	120	ns	10 ns + (1,0 ns/pF) $C_L$
	10			30	60	ns	9 ns + (0,42 ns/pF) $C_L$
	15			20	40	ns	6 ns + (0,28 ns/pF) $C_L$
Set-up time D $\rightarrow$ CP	5	$t_{su}$	25	-15		ns	see waveforms Figs 4 and 5
	10		25	-10		ns	
	15		20	-5		ns	
Hold time D $\rightarrow$ CP	5	$t_{hold}$	40	20		ns	
	10		20	10		ns	
	15		15	8		ns	
Minimum clock pulse width; LOW	5	$t_{WCPL}$	60	30		ns	
	10		30	15		ns	
	15		20	10		ns	
Minimum MR pulse width; HIGH	5	$t_{WMRH}$	80	40		ns	
	10		30	15		ns	
	15		24	12		ns	
Recovery time for MR	5	$t_{RMR}$	50	20		ns	
	10		30	10		ns	
	15		20	5		ns	
Maximum clock pulse frequency	5	$f_{max}$	7	15		MHz	
	10		15	30		MHz	
	15		22	44		MHz	

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	$V_{DD}$ V	TYPICAL FORMULA FOR P ( $\mu$ W)	
Dynamic power dissipation per package (P)	5	$1\ 500 f_i + \sum (f_o C_L) \times V_{DD}^2$	where $f_i$ = input freq. (MHz) $f_o$ = output freq. (MHz) $C_L$ = load capacitance (pF) $\sum (f_o C_L)$ = sum of outputs $V_{DD}$ = supply voltage (V)
	10	$6\ 300 f_i + \sum (f_o C_L) \times V_{DD}^2$	
	15	$17\ 000 f_i + \sum (f_o C_L) \times V_{DD}^2$	

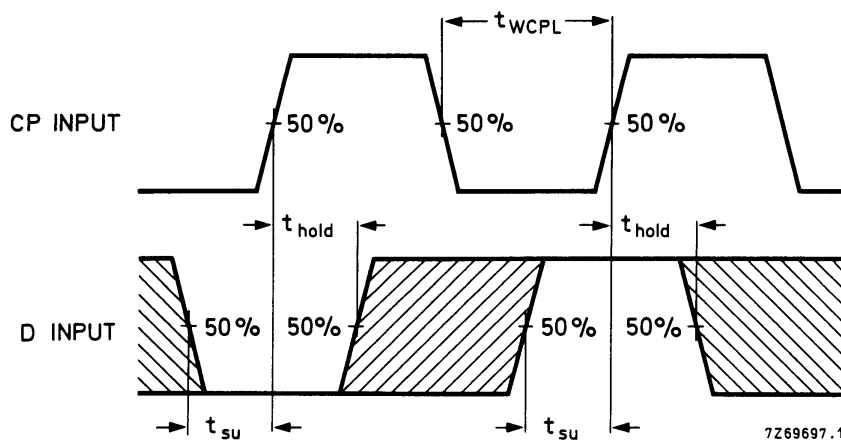


Fig.4 Waveforms showing set-up times, hold times and minimum clock pulse width. Set-up and hold times are shown as positive values but may be specified as negative values.

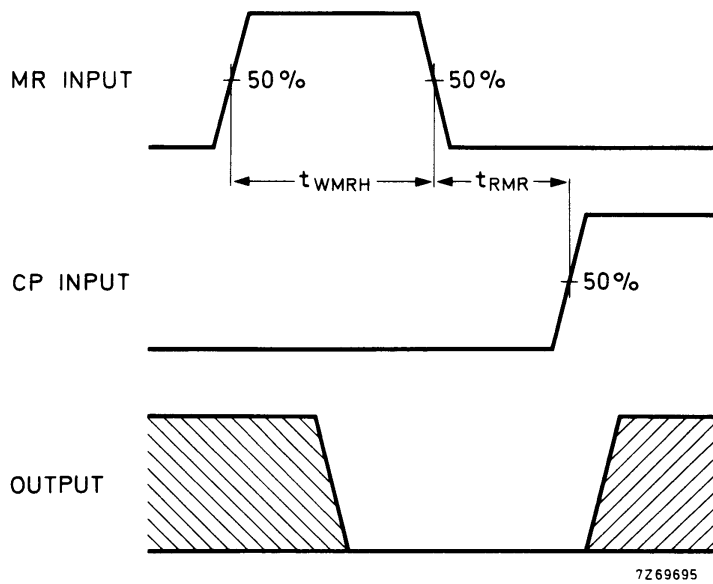
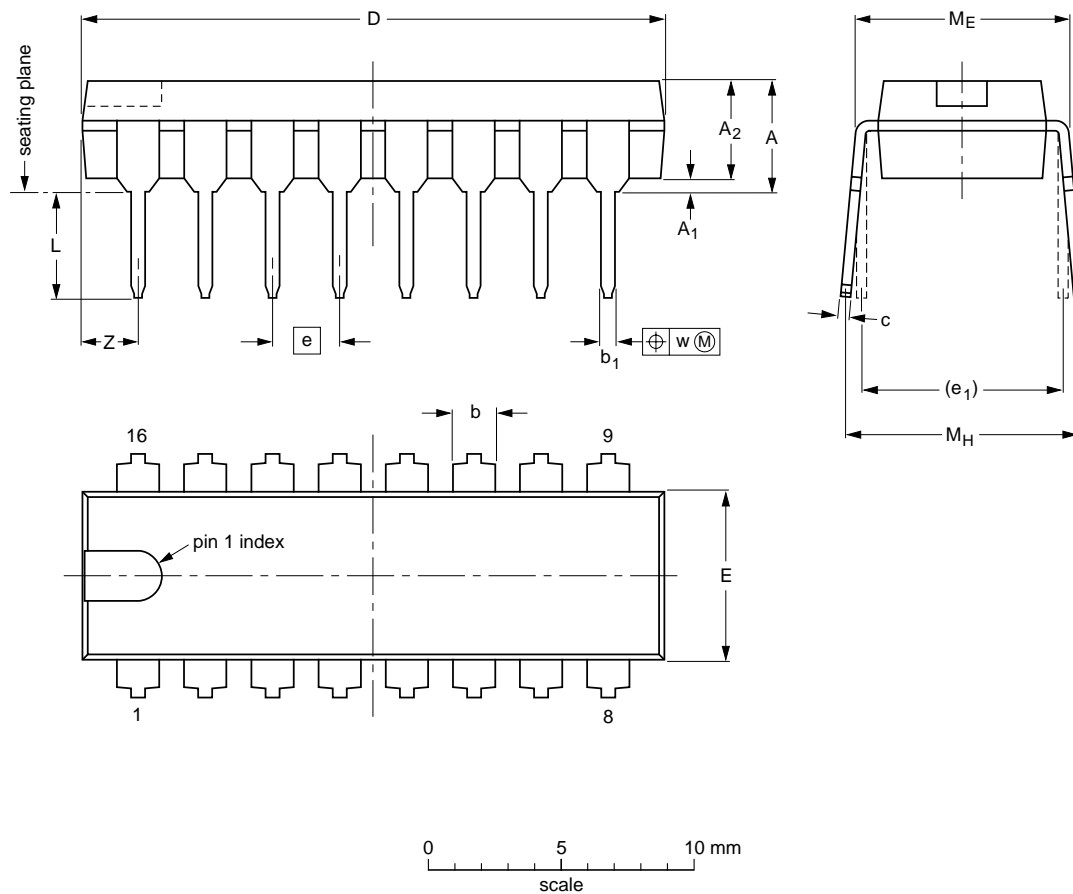


Fig.5 Waveforms showing recovery time for MR and minimum MR pulse width.

DIP16: plastic dual in-line package; 16 leads (300 mil); long body

SOT38-1



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A <sub>1</sub> min.	A <sub>2</sub> max.	b	b <sub>1</sub>	c	D <sup>(1)</sup>	E <sup>(1)</sup>	e	e <sub>1</sub>	L	M <sub>E</sub>	M <sub>H</sub>	w	Z <sup>(1)</sup> max.
mm	4.7	0.51	3.7	1.40 1.14	0.53 0.38	0.32 0.23	21.8 21.4	6.48 6.20	2.54	7.62	3.9 3.4	8.25 7.80	9.5 8.3	0.254	2.2
inches	0.19	0.020	0.15	0.055 0.045	0.021 0.015	0.013 0.009	0.86 0.84	0.26 0.24	0.10	0.30	0.15 0.13	0.32 0.31	0.37 0.33	0.01	0.087

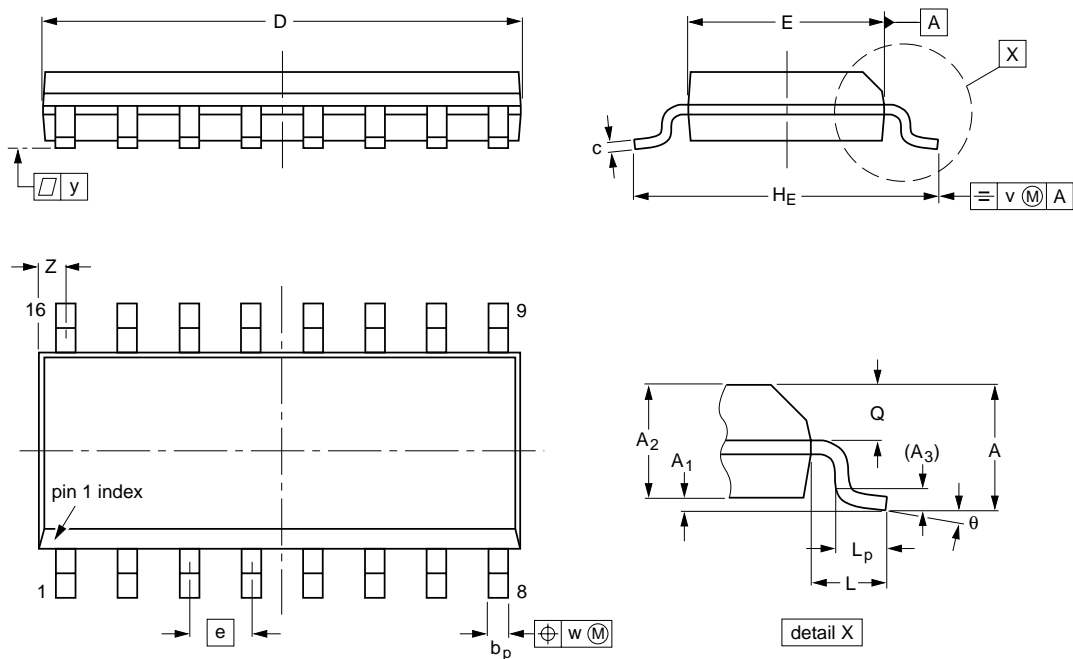
Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	EIAJ			
SOT38-1	050G09	MO-001AE				92-10-02 95-01-19

**SO16: plastic small outline package; 16 leads; body width 3.9 mm**

**SOT109-1**



**DIMENSIONS (inch dimensions are derived from the original mm dimensions)**

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	c	D <sup>(1)</sup>	E <sup>(1)</sup>	e	H <sub>E</sub>	L	L <sub>p</sub>	Q	v	w	y	Z <sup>(1)</sup>	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	10.0 9.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8° 0°
inches	0.069	0.010 0.004	0.057 0.049	0.01	0.019 0.014	0.0100 0.0075	0.39 0.38	0.16 0.15	0.050	0.244 0.228	0.041	0.039 0.016	0.028 0.020	0.01	0.01	0.004	0.028 0.012	

**Note**

1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	EIAJ			
SOT109-1	076E07S	MS-012AC				95-01-23 97-05-22